# Fieldbus system

# **Operation Manual**

### EX600-AX/EX600-AY/EX600-AM

Thank you for purchasing an SMC EX600 Series Fieldbus system Please read this manual carefully before operating the product and make sure you understand its capabilities and limitations. Please keep this manual handy for future reference.

To obtain more detailed information about operating this product, please refer to the SMC website (URL http://www.smcworld.com) or contact SMC directly.

## Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage

These instructions indicate the level of potential hazard with the labels of "Caution", "Warning" or "Danger". They are all important notes for safety and must be followed in addition to International standards (ISO/IEC), Japan Industrial Standards (JIS) and other safety regulations.

<b>▲</b> Caution:	CAUTION indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.
A Warning:	WARNING indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
▲ Danger:	DANGER indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.
Operator	

#### Operato

- + This operation manual is intended for those who have knowledge of machinery using pneumatic equipment, and have sufficient knowledge of assembly. operation and maintenace of such equipment. Only those persons are allowed to perform assembly, operation and maintenance. Read and understand this operation manual carefully before assembling
- operating or providing maintenance to the product.
- ■Safety Instructions

	🛆 Warning
Do i An i	not disassemble, modify (including changing the printed circuit board) or repair. njury or failure can result.
Do r Fire	not operate the product outside of the specifications. not use for flammable or harmful fluids. , malfunction, or damage to the product can result. ify the specifications before use.
Fire	not operate in an atmosphere containing flammable or explosive gases. or an explosion can result. s product is not designed to be explosion proof.
•Pro	sing the product in an interlocking circuit: vide a double interlocking system, for example a mechanical system. eck the product regularly for proper operation. erwise malfunction can result, causing an accident.
•Tur •Sto ma	following instructions must be followed during maintenance: m off the power supply. by the air supply, exhaust the residual pressure and verify that the air is released before performing intenance. arwise an injury can result.
	<b>∆</b> Caution
•Do •Tał The •Wh	en handling the unit or assembling/replacing units: not touch the sharp metal parts of the connector or plug for connecting units. ke care not to thi your hand when disassembling the unit. e connecting portions of the unit are firmly joined with seals. uen joining units, take care not to get fingers caught between units. njury can result.
Stop	er maintenance is complete, perform appropriate functional inspections. p operation if the equipment does not function properly. ety cannot be assured in the case of unexpected malfunction.
	vide grounding to assure the safety and noise resistance of the Fieldbus system.

• The direct current power supply to combine should be UL1310 Class2 power supply when conformity to UL is necessary

## Maintenance

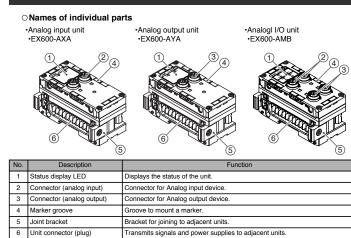
•Maintenance should be performed according to the Safety Instructions. •Perform regular maintenance and inspections. There is a risk of unexpected malfunction. •Do not use solvents such as benzene, thinner etc. to clean each unit.

They could damage the surface of the body and erase the markings on the body. Use a soft cloth to remove stains.

For heavy stains, use a cloth soaked with diluted neutral detergent and fully squeezed, then wipe up the stains again with a dry cloth.

Refer to the SMC website (URL http://www.smcworld.com) to obtain more detailed information about maintenance.

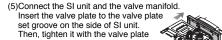
## Names and Functions of Product



## Assembly

CE

- O Composing the unit as a manifold
- (1)Connect the unit to the end plate. The Digital unit, Analog unit can be connected in any
- orde Tighten the bracket of the joint using tightening torque 1.5 to 1.6 Nm.
- (2) Add more units Up to 10 units (including the SI unit) can be connected to one manifold.
- (3)Connecting the SI unit. After connecting the necessary units, connect the SI unit.
- Connecting method is the same as above (1), (2). (4)Mounting the valve plate Mount the valve plate (EX600-ZMV□) to the valve manifold using the valve set screws. (M3x8) Apply 0.6 to 0.7 Nm tightening torque to the



set screws (M4x6) to fix the plate. Tightening torgue for set screws 0.7 to 0.8 Nm

## Mounting and Installation

#### ■Installation

screws

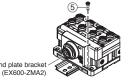
- Direct mounting (1)When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB1) before mounting using 2-M4x5 screws. Tightening torque: 0.7 to 0.8 Nm.
- (2)Fix and tighten the end plates at one end of the unit. (M4)
- Tightening torque: 0.7 to 0.8 Nm. Fix the end plate at the valve side while referring to the operation manual of the corresponding valve manifold.

#### ·DIN rail mounting

- (Available for series other than SY series. Refer to the catalog for SY series.) (1)When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB2) before mounting, using 2-M4x6 screws. Tightening torque: 0.7 to 0.8 Nm.
- (2)Mount the end plate bracket (EX600-ZMA2) to the end plate at the opposite end to the valves, using 2-M4x14 Tightening torque: 0.7 to 0.8 Nm.

(3)Hook the DIN rail mounting groove to the DIN rail.

(4)Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked. (5)Fix the manifold by tightening the DIN rail fixing screws of the EX600-ZMA2. (M4x20) Tightening torque: 0.7 to 0.8 Nm. The tightening torque at the valve side depends on the valve type. Refer to the operation manual of the corresponding valve manifold. End plate bracke



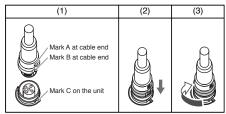
#### ■Wiring

•Connect the M12 or M8 connector cable. M12 connector is applicable for SPEEDCON connector

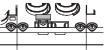
SPEEDCON connector wiring method is explained below. (1)Align the mark B on the metal bracket of the cable side connector (plug/socket) with the mark A

(2)Align the mark C on the unit and insert the connector into the unit vertically. If they are not aligned, the connector cannot be joined properly.

#### (3)When the mark B of the connector has been turned 180 degrees (1/2 turn), wiring is completed. Confirm that the connection is not loose. If turned too far, it will become hard to remove the connector



·Mounting the marker Signal name of the input or output devices and unit address can be written to the marker, and it can be installed to each unit. Mount the marker (EX600-ZT1) into the marker groove as required.



<ul> <li>Connector</li> </ul>	pin	assig	nment

(EX600-ZMVD)

ate reinforcing brace

ediate reinforcing brace

E.

(EX600-ZMB1)

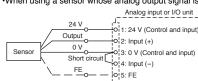
(FX600-ZMB2)

DIN rail mounting or

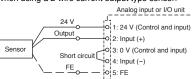
		Signal name			
Configuration	Pin number	Analog input unit EX600-AXA EX600-AYA	Analog I/O unit EX600-AMB		
				Input connector	Output connector
	1	24 V (control and input)	24 V (output)	24 V (control and input)	24 V (output)
	2	Input +	Output	Input +	Output
(šoč)	3	0 V (control and input)	0 V (output)	0 V (control and input)	0 V (output)
$\langle \mathfrak{S} \rangle$	4	Input -	0 V (output)	Input -	0 V (output)
4 ) 3	5	FE	FE	FE	FE

·Examples of wiring with input devices

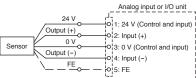
#### •When using a sensor whose analog output signal is 0 V standard type.



\_\_\_\_\_ •When using a 2-wire current output type sensor.



·When using a differential output type sensor



#### Precautions for handling

When an analog sensor is connected to the Analog input or I/O unit, pay attention to the following cautions.

EX600 analog input has a differential input specification, and it receives 2-pin (input +) signal based on 4-pin (input -). Because of the specification, if 4-pin is not connected, it will not be able to read the signal input properly. Therefore, when using an analog sensor that does not have the differential output type, 3-pin and 4-pin should be connected externally.

# LED Display

#### The status display LED shows the following unit state.

<ul> <li>Analog input unit</li> </ul>	1		
Display	Content		
Off	The power supply for control and input is Off.		
Green LED is On	The product is operating normally.		
Red LED is On	The power supply of input device has a short circuit.		
0 and 1 red LEDs are On	Either of the following conditions: •The current value of the analog input device has exceeded the upper or lower limit. •When the range is set by current input type, voltage is input from the analog input device.		
Red LED is flashing	Either of the following conditions: •The upper or lower limit of the range is exceeded. •The upper or lower limit of the measuring value (with user's setting value) is exceeded.		
An allow as the device of the			

Analog output unit			
Display	Content		
Off	The power supply for control and input is Off.		
Green LED is On	The product is operating normally.		
Red LED is On	Red LED is On The power supply of output device has a short circuit.		
Red LED is flashing The upper or lower limit of the output value (with user's setting value) is exceeded.			
<ul> <li>Analog I/O unit</li> </ul>			
Display	Content		
Off	The power supply for control and input is Off.		
Green LED is On	The product is operating normally		

	Green LED Is On		The product is operating normally.
	Red LED is	On	The power supply of input or output devices has a short circuit.
	0 and 1 red LEDs are On Input		Either of the following conditions: -The current value of the analog input device has exceeded the upper or lower limit. -When the range is set by current input type, voltage is input from the analog input device.
	Red LED is flashing	Input	Either of the following conditions: -The upper or lower limit of the range is exceeded. -The upper or lower limit of the measuring value (with user's setting value) is exceeded.
		Output	The upper or lower limit of the output value (with user's setting value) is exceeded.

Refer to the SMC website (URL http://www.smcworld.com) to obtain more detailed information about LED display.

## Troubleshooting

Refer to the LED Display. Refer to the SMC website (URL http://www.smcworld.com) to obtain more detailed information about troubleshooting

## Specification

Model		EX600-AXA	EX600-AYA	EX600-AMB	
Power Control and input		24 VDC Class2, 2 A			
supply	Output	-	24 VDC Class2, 2 A		
Input signal range		-10 V to 10 V -20 mA to 20 mA	-	0 V to 10 V 0 mA to 20 mA	
Output signal range		-	0 V to 10 V 0 mA to 20 mA	0 V to 10 V 0 mA to 20 mA	
Operating temperature range		-10 to 50 °C (Max. surrounding air temperature rating: 50 °C)			
Storage temperature range		-20 to 60 °C			
Poll	ution degree	For use in Pollution Degree 2 Environment (UL508)			
Vibration resistance 57 to 1			7 Hz: constant amplitude 0.75 50 Hz: constant acceleration 4 direction X, Y and Z respectiv	19 m/s <sup>2</sup>	
Impa	Impact resistance 147 m/s <sup>2</sup> 3 times each in directions of X, Y and Z respectively (De-energized)				

\*1: Input terminals are not isolated from Power source. \*2: Do not connect outside Power source to Input and Output terminals

Refer to the product catalog or SMC website (URL http://www.smcworld.com) to

obtain more detailed information about product specifications.

## Analog characteristics

Refer to the SMC website (URL http://www.smcworld.com) to obtain more detailed information about analog characteristics.

## Outline with Dimensions

Refer to the product catalog or SMC website (URL http://www.smcworld.com) to obtain more detailed information about outline dimensions.

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Note: Specifications are subject to change without prior notice and any obligation on the part of the manufacturer. © 2009 SMC Corporation All Rights Reserved